

1. Show that the function $f(t, x) = x^2 e^{-t^2} \sin t$ is Lipschitz continuous for $x \in [0, 2]$.
2. Find the Lagrange and Newton forms of the interpolating polynomial for the data

$$\frac{x}{f(x)} \left\| \begin{array}{c|c|c} -2 & 0 & 1 \\ \hline 0 & 1 & -1 \end{array} \right.$$

Write both polynomials in the form $a + bx + cx^2$ to verify that they are identical as functions.

3. The polynomial p of degree $\leq n$ that interpolates a given functions f at $n + 1$ prescribed nodes is uniquely defined. Hence, there is a mapping $f \mapsto p$. Denote this mapping by L and show that

$$Lf = \sum_{i=0}^n f(x_i) \ell_i.$$

Show that L is linear, i.e., $L(af + bg) = aLf + bLg$, where f and g are given functions, and a, b are real constants.

4. Prove that the mapping, L , in Problem 3 has the property that $Lq = q$ for every polynomial q of degree at most n .
5. Prove that if we take *any* set of 23 nodes in the interval $[-1, 1]$ and interpolate the function $f(x) = \cosh x$ with a polynomial p of degree 22, then the relative error $|p(x) - f(x)|/|f(x)|$ is no greater than 5×10^{-16} on $[-1, 1]$.
6. (a) Approximate the function $f(x) = e^{x/2}$ over the interval $[1, 9]$ by a fourth-degree polynomial in two ways: using a Taylor polynomial centered at $x_0 = 5$, and using the Lagrange form of the interpolating polynomial with $x_0 = 1$, $x_1 = 3$, $x_2 = 5$, $x_3 = 7$, and $x_4 = 9$.
 (b) Plot the error estimates for these two approaches (using Taylor's Theorem and the Lagrange form of the interpolating polynomial) for $x \in [0, 12]$.
 (c) Use your favorite software to plot the actual error for these approximants on $[0, 12]$. Comment.
7. Prove that

$$\det \begin{vmatrix} 1 & x_0 & x_0^2 & \cdots & x_0^n \\ 1 & x_1 & x_1^2 & \cdots & x_1^n \\ 1 & x_2 & x_2^2 & \cdots & x_2^n \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & x_n & x_n^2 & \cdots & x_n^n \end{vmatrix} = \prod_{0 \leq j < k \leq n} (x_k - x_j)$$

$$= (x_n - x_0)(x_n - x_1)(x_n - x_2) \cdots (x_n - x_{n-1}) \cdots$$

$$(x_3 - x_0)(x_3 - x_1)(x_3 - x_2)(x_2 - x_0)(x_2 - x_1)(x_1 - x_0).$$