

1. Construct a  $3 \times 4$  matrix  $A$  and  $3 \times 1$  column vectors  $\mathbf{b}$  and  $\mathbf{c}$  such that the *augmented matrix*  $(A \ \mathbf{b})$  is the augmented matrix for an inconsistent linear system  $A\mathbf{x} = \mathbf{b}$ , but  $(A \ \mathbf{c})$  is the augmented matrix for a consistent system.
2. Assume that  $m < n$  are positive integers and explain why a homogeneous linear system  $A\mathbf{x} = \mathbf{0}$  of  $m$  equations in  $n$  unknowns must always possess infinitely many solutions.
3. Consider the linear system  $A\mathbf{x} = \mathbf{b}$  with

$$A = \begin{pmatrix} 2 & 2 & 3 \\ 4 & 8 & 12 \\ 6 & 2 & \alpha \end{pmatrix}, \quad \mathbf{b} = \begin{pmatrix} 0 \\ -4 \\ 4 \end{pmatrix}.$$

- (a) Determine all values of  $\alpha$  for which the system is *consistent*, i.e., for which the system has at least one solution.
  - (b) Determine all values of  $\alpha$  for which there is a unique solution, and compute the solutions for these cases.
  - (c) Determine all values of  $\alpha$  for which there are infinitely many solutions, and give the general solution for these cases.
4. The *trace* of a square matrix  $A$  is given by the sum of its diagonal elements, i.e.,

$$\text{trace}(A) = \sum_{i=1}^n [A]_{ii}.$$

Show that  $\text{trace}(\cdot)$  is a linear function.

5. Let  $A$  be an  $m \times n$  matrix. The *transpose*  $A^T$  of  $A$  is defined by  $[A^T]_{ij} = [A]_{ji}$ . Use this definition to prove that

$$(A + B)^T = A^T + B^T$$

provided both  $A$  and  $B$  are  $m \times n$  matrices.

6. Prove or disprove: If  $A, B$  and  $C$  are matrices of compatible sizes, then  $AB = AC$  implies  $B = C$ .
7. Let

$$E = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 3 & 0 & 1 \end{pmatrix}$$

and let  $A$  be an arbitrary  $3 \times 3$  matrix.

- (a) Describe the rows of  $EA$  in terms of the rows of  $A$ .
  - (b) Describe the columns of  $AE$  in terms of the columns of  $A$ .
8. For all  $n \times k$  matrices  $A$  and  $k \times n$  matrices  $B$ , show that the block matrix

$$L = \begin{pmatrix} I - BA & B \\ 2A - ABA & AB - I \end{pmatrix}$$

satisfies  $L^2 = I$ , and therefore is a so-called *involutory* matrix.